

Motivation and overview

- **Score-based generative models** (SGMs) [6, 2] have shown great success for **modelling flexible distributions**.
- **Data** is often naturally described on **Riemannian manifolds** such as spheres, torii, and Lie groups, whereas standard SGMs assume a **flat geometry**, making them ill-suited.
- We introduce **Riemannian SGMs**, a model which admits the parametrization of **flexible distributions on manifolds** by simulating the time reversal of continuous diffusion process.

Contributions

- We establish that the corresponding **time-reversal process** is also a diffusion whose drift includes the Stein score.
- Rely on Geodesic Random Walk for **sampling** processes [3].
- We provide theoretical **convergence bounds** for RSGMs.
- We **empirically demonstrate** that RSGMs perform and scale better than recent baselines [4, 5].

Ingredient \ Space	Euclidean	Manifolds / Compact manifolds
Forward process	Ornstein–Uhlenbeck	Langevin Dynamics / Brownian
Base distribution p_{ref}	Gaussian	Wrapped Normal / Uniform
Time reversal	[1, Theorem 4.9]	Theorem 1
Sampling of the forward	Direct	Geodesic Random Walk
Sampling of the backward	Euler–Maruyama	Geodesic Random Walk

Table 1: SGM on Euclidean spaces vs RSGM on Riemannian manifolds.

Noising and denoising processes

We rely on **Langevin dynamics** for the forward noising process

$$d\mathbf{X}_t = -\frac{1}{2} \nabla_{\mathbf{X}_t} U(\mathbf{X}_t) dt + d\mathbf{B}_t^M, \quad (1)$$

which admits the invariant density $d\rho_{\text{ref}}/d\text{Vol}_{\mathcal{M}}(x) \propto e^{-U(x)}$. A convenient choice for p_{ref} is the **Wrapped normal distribution**, and on compact manifolds we choose the uniform $p_{\text{ref}} = 1/\text{Vol}_{\mathcal{M}}$.

Theorem 1: Time-reversed diffusion

Let $(\mathbf{Y}_t)_{t \in [0, T]} = (\mathbf{X}_{T-t})_{t \in [0, T]}$ the time-reversal. Under mild assumptions on p_0 and on p_t the density of $\mathbb{P}_t = \mathcal{L}(\mathbf{X}_t)$, then

$$d\mathbf{Y}_t = \left\{ \frac{1}{2} \nabla_{\mathbf{Y}_t} U(\mathbf{Y}_t) + \nabla \log p_{T-t}(\mathbf{Y}_t) \right\} dt + d\mathbf{B}_t^M. \quad (2)$$



(a) GRW vs Brownian motion density

(b) GRW step

(c) Trajectory

Algorithm 1 GRW (Geodesic Random Walk)

Require: $T, N, X_0^i, b, \sigma, P, \gamma = T/N$

- 1: **for** $k \in \{0, \dots, N-1\}$ **do**
- 2: $Z_{k+1} \sim N(0, \text{Id})$ ▷ Gaussian on tangent space $T_x \mathcal{M}$
- 3: $W_{k+1} = \gamma b(k\gamma, X_k^i) + \sqrt{\gamma} \sigma(k\gamma, X_k^i) Z_{k+1}$ ▷ Euler–Maruyama step
- 4: $X_{k+1}^i = \text{exp}_{X_k^i}[W_{k+1}]$ ▷ Geodesic projection onto \mathcal{M}

Score-based generative modelling

Algorithm 2 RSGM (Riemannian Score-Based Generative Model)

- Require:** $\varepsilon, T, N, \{X_0^m\}_{m=1}^M, \text{loss}, \mathbf{s}, \theta_0, N_{\text{iter}}, p_{\text{ref}}, P$
- 1: **for** $n \in \{0, \dots, N_{\text{iter}}-1\}$ **do** // TRAINING //
 - 2: $X_0 \sim (1/M) \sum_{m=1}^M \delta_{X_0^m}$ ▷ Random mini-batch from dataset
 - 3: $t \sim U([\varepsilon, T])$ ▷ Uniform sampling between ε and T
 - 4: $\mathbf{X}_t = \text{GRW}(t, N, X_0, 0, \text{Id}, P)$ ▷ Approximate forward diffusion with Algorithm 1
 - 5: $\ell(\theta_n) = \ell_t(T, N, X_0, \mathbf{X}_t, \text{loss}, \mathbf{s}_{\theta_n})$ ▷ Compute score matching loss from Table 2
 - 6: $\theta_{n+1} = \text{optimizer_update}(\theta_n, \ell(\theta_n))$ ▷ ADAM optimizer step
 - 7: $\theta^* = \theta_{N_{\text{epoch}}}$
 - 8: $Y_0 \sim p_{\text{ref}}$ // SAMPLING // ▷ Sample from uniform distribution
 - 9: $b_{\theta^*}^*(t, x) = \frac{1}{2} \nabla_x U(x) + \mathbf{s}_{\theta^*}(T-t, x)$ for any $t \in [0, T], x \in \mathcal{M}$ ▷ Reverse process drift
 - 10: $\{Y_k\}_{k=0}^N = \text{GRW}(T, N, Y_0, b_{\theta^*}, \text{Id}, P)$ ▷ Approximate reverse diffusion with Algorithm 1

- The following result ensures that RSGM generates samples which are close to p_0 .

Theorem 2: Quantitative bounds for RSGM

Under mild assumption over p_0 , assuming that \mathcal{M} is compact and that there exists $M \geq 0$ such that for any $t \in [0, T]$ and $x \in \mathcal{M}$, $\|\mathbf{s}_{\theta^*}(t, x) - \nabla \log p_t(x)\| \leq M$, with $\mathbf{s}_{\theta^*} \in C([0, T], \mathcal{X}(\mathcal{M}))$. Then if $T > 1/2$, there exists $C \geq 0$ independent on T s.t.

$$\mathbf{W}_1(\mathcal{L}(Y_N), p_0) = C(e^{-\lambda T} + \sqrt{T/2M} + e^T \gamma^{1/2}), \quad (3)$$

where \mathbf{W}_1 is the Wasserstein distance of order one on the probability measures on \mathcal{M} .

Score matching on compact manifolds

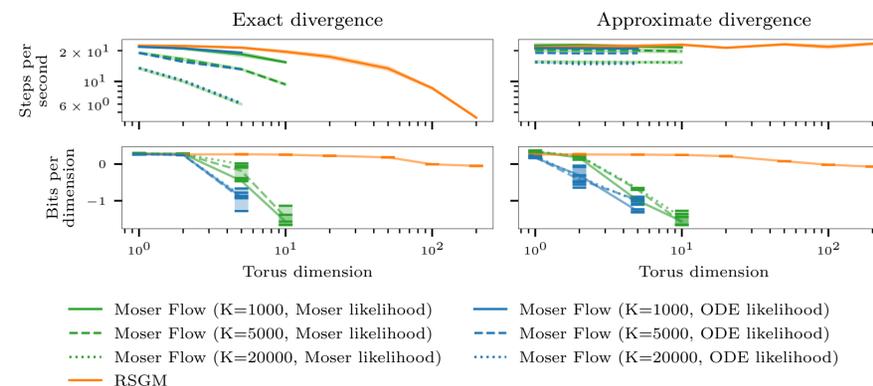
- The heat kernel is given by $p_{t|0}(x_t|x_0) = \sum_{j \in \mathbb{N}} e^{-\lambda_j t} \phi_j(x_0) \phi_j(x_t)$ (Sturm–Liouville).
- Truncation: $S_{J,t}(x_0, x_t) \triangleq \nabla_{x_t} \log \sum_{j=0}^J e^{-\lambda_j t} \phi_j(x_0) \phi_j(x_t) \approx \nabla_{x_t} \log p_t(x_t|x_0)$.

Loss	Approximation	Loss function	Requirements		Complexity
			$p_{t 0}$	$\exp_{x_t}^{-1}$	
$\ell_{t 0}$ (DSM)	None	$\frac{1}{2} \mathbb{E} [\ \mathbf{s}(\mathbf{X}_t) - \nabla_{\mathbf{X}_t} \log p_t(\mathbf{X}_t x_0)\ ^2]$	–	–	–
	Truncation	$\frac{1}{2} \mathbb{E} [\ \mathbf{s}(\mathbf{X}_t) - S_{J,t}(\mathbf{X}_0, \mathbf{X}_t)\ ^2]$	✓	✗	$\mathcal{O}(1)$
	Varhadan	$\frac{1}{2} \mathbb{E} [\ \mathbf{s}(\mathbf{X}_t) - \exp_{x_t}^{-1}(\mathbf{X}_0)/t\ ^2]$	✗	✓	$\mathcal{O}(1)$
ℓ_t^{im} (ISM)	Deterministic	$\mathbb{E} [\frac{1}{2} \ \mathbf{s}(\mathbf{X}_t)\ ^2 + \text{div}(\mathbf{s})(\mathbf{X}_t)]$	✗	✗	$\mathcal{O}(d)$
	Hutchinson	$\mathbb{E} [\frac{1}{2} \ \mathbf{s}(\mathbf{X}_t)\ ^2 + \varepsilon^T \partial \mathbf{s}(\mathbf{X}_t) \varepsilon]$	✗	✗	$\mathcal{O}(1)$

Table 2: Computational complexity of score matching losses w.r.t. score network passes.

Synthetic data on torii

- We consider a wrapped Gaussian target distribution on $\mathbb{T}^d = \mathbb{S}^1 \times \dots \times \mathbb{S}^1$.



Earth science datasets on the sphere

- We evaluate RSGMs on occurrences of earth and climate science events distributed on the surface of the earth.

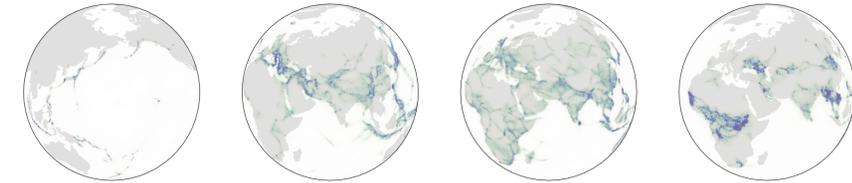


Figure 2: Trained RSGM on earth sciences data, with density in green-blue.

Method	Volcano	Earthquake	Flood	Fire
Mixture of Kent	$-0.80_{\pm 0.47}$	$0.33_{\pm 0.05}$	$0.73_{\pm 0.07}$	$-1.18_{\pm 0.06}$
Riemannian CNF	$-6.05_{\pm 0.61}$	$0.14_{\pm 0.23}$	$1.11_{\pm 0.19}$	$-0.80_{\pm 0.54}$
Moser Flow	$-4.21_{\pm 0.17}$	$-0.16_{\pm 0.06}$	$0.57_{\pm 0.10}$	$-1.28_{\pm 0.05}$
Stereographic Score-Based	$-3.80_{\pm 0.27}$	$-0.19_{\pm 0.05}$	$0.59_{\pm 0.07}$	$-1.28_{\pm 0.12}$
Riemannian Score-Based	$-4.92_{\pm 0.25}$	$-0.19_{\pm 0.07}$	$0.45_{\pm 0.17}$	$-1.33_{\pm 0.06}$
Dataset size	827	6120	4875	12809

Table 3: Negative log-likelihood. Confidence intervals computed over 5 runs.

Method	Training	Likelihood evaluation	Sampling
RCNF [4]	Solve ODE $\mathcal{O}(dN)$	Solve ODE $\mathcal{O}(dN)$	Solve ODE $\mathcal{O}(N)$
Moser [5]	Computing div $\mathcal{O}(dk)$ or $\mathcal{O}(k)$	Solve ODE $\mathcal{O}(dN)$	Solve ODE $\mathcal{O}(N)$
RSGM	Score matching $\mathcal{O}(d)$ or $\mathcal{O}(1)$	Solve ODE $\mathcal{O}(dN)$	Solve SDE $\mathcal{O}(N^*)$

Table 4: Computational complexity w.r.t. neural network passes.

Synthetic data on SO(3)

- We consider a mixture of wrapped Gaussian target on $\text{SO}_3(\mathbb{R}) = \{Q \in M_3(\mathbb{R}) : QQ^T = I_3, \det(Q) = 1\}$.

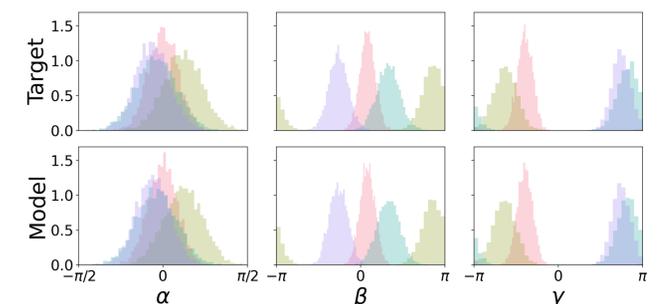


Figure 3: Histograms of $\text{SO}_3(\mathbb{R})$ samples from a target mixture distribution.

Method	$M = 16$		$M = 32$		$M = 64$	
	$\log p$	NFE	$\log p$	NFE	$\log p$	NFE
Moser Flow	$0.85_{\pm 0.03}$	$2.3_{\pm 0.5}$	$0.17_{\pm 0.03}$	$2.3_{\pm 0.9}$	$-0.49_{\pm 0.02}$	$7.3_{\pm 1.4}$
Exp-wrapped SGM	$0.87_{\pm 0.04}$	$0.5_{\pm 0.1}$	$0.16_{\pm 0.03}$	$0.5_{\pm 0.0}$	$-0.58_{\pm 0.04}$	$0.5_{\pm 0.0}$
RSGM	$0.89_{\pm 0.03}$	$0.1_{\pm 0.0}$	$0.20_{\pm 0.03}$	$0.1_{\pm 0.0}$	$-0.49_{\pm 0.02}$	$0.1_{\pm 0.0}$

Table 5: Log-likelihood and neural function evaluations (NFE) in 10^3 .

References

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